

TWISTED TOMEI MANIFOLDS AND TODA LATTICE*

LUIS CASIAN^a AND YUJI KODAMA^b

ABSTRACT. This paper begins with an observation that the isospectral leaves of the signed Toda lattice as well as the Toda flow itself may be constructed from the Tomei manifolds by cutting and pasting along certain chamber walls inside a polytope. It is also observed through examples that although there is some freedom in this procedure of cutting and pasting the manifold and the flow, the choices that can be made are not arbitrary. We proceed to describe a procedure that begins with an action of the Weyl group on a set of signs; it uses the Convexity Theorem in [3] and combines the resulting polytope with the chosen Weyl group action to paste together a compact manifold. This manifold which is obtained carries an action of the Weyl group and a Toda lattice flow which is related to this action. This construction gives rise to a large family of compact manifolds which is parametrized by twisted sign actions of the Weyl group. For example, the trivial action gives rise to Tomei manifolds and the standard action of the Weyl group on the connected components of a split Cartan subgroup of a split semisimple real Lie group gives rise to the isospectral leaves of the signed Toda lattice. This clarifies the connection between the polytope in the Convexity Theorem and the topology of the compact smooth manifolds arising from the isospectral leaves of a Toda flow. Furthermore, this allows us to give a uniform treatment to two very different cases that have been studied extensively in the literature producing new cases to look at. Finally we describe the unstable manifolds of the Toda flow for these more general manifolds and determine which of these give rise to cycles.

1. INTRODUCTION

In [12], Tomei constructed a compact and orientable smooth manifold as an isospectral real manifold generated by the Toda lattice equation on the set of the tridiagonal symmetric matrices. Let us begin with a brief description of this manifold: Let Z be the set of $(l+1) \times (l+1)$ tridiagonal trace zero matrices,

$$Z = \left\{ \begin{pmatrix} a_1 & b_1 & 0 & \cdots & 0 \\ b_1 & a_2 & b_2 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & \ddots & a_l & b_l \\ 0 & \cdots & \cdots & b_l & a_{l+1} \end{pmatrix} : \sum_{i=1}^{l+1} a_i = 0, b_i \neq 0 \right\}. \quad (1.1)$$

a) Department of Mathematics, The Ohio State University, Columbus, OH 43210

E-mail address: casian@math.ohio-state.edu

b) Department of Mathematics, The Ohio State University, Columbus, OH 43210

E-mail address: kodama@math.ohio-state.edu

*Supported by NSF grant DMS0071523.

According to the signs of b_i 's, the set Z is a disjoint union of 2^l connected components;

$$Z = \bigcup_{\epsilon \in \mathcal{E}} Z_\epsilon, \quad (1.2)$$

where the set of signs is defined by

$$\mathcal{E} := \{ (\epsilon_1, \dots, \epsilon_l) \in \{\pm 1\}^l : \epsilon_k = \text{sign}(b_k), k = 1, \dots, l \}. \quad (1.3)$$

An isospectral leaf is a subset of Z consisting of tridiagonal matrices with fixed eigenvalues $\lambda_1, \dots, \lambda_{l+1}$ with $\sum_{k=1}^{l+1} \lambda_k = 0$. We consider in this paper only the case with distinct eigenvalues. Any point of the leaf is obtained from the diagonal matrix $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_l)$ by conjugation, that is, they lies on an orbit of the adjoint action of the group of orthogonal matrices on the set of symmetric matrices,

$$\mathcal{O}_\Lambda = \{ \text{Ad}_p \Lambda : p \in SO(l+1) \}. \quad (1.4)$$

The Toda lattice is given by the following matrix equation for $X(t) \in Z$ with a parameter $t \in \mathbb{R}$,

$$\frac{dX}{dt} = [P, X] \quad (1.5)$$

where the matrix P is the skew symmetrization of X , i.e. $P = X_+ - X_-$ with X_+ (X_-) the upper (lower) triangular part of X . The solution defines an orbit in \mathcal{O}_Λ ,

$$X(t) = \text{Ad}_{Q(t)} X(0), \quad (1.6)$$

where the matrix function $Q(t) \in SO(l+1)$ is given by the QR-factorization of the matrix $\exp(tX(0))$,

$$\exp(tX(0)) = Q(t)R(t), \quad (1.7)$$

with an upper triangular matrix $R(t)$. The isospectral leaf can be also expressed as the inverse image of the symmetric polynomials $\gamma_1, \dots, \gamma_l$ of the eigenvalues,

$$Z(\gamma) = \mathcal{I}^{-1}(\gamma) \cap Z \quad (1.8)$$

where $\gamma = (\gamma_1, \dots, \gamma_l) \in \mathbb{R}^l$ is the image of the Chevalley invariants $\mathcal{I} = (I_1, \dots, I_l) : Z \rightarrow \mathbb{R}^l$ defined in the characteristic polynomial of the matrix $X \in Z$,

$$\det(\lambda I - X) = \lambda^{l+1} - \sum_{k=1}^l (-1)^k I_k \lambda^{l-k} = 0.$$

It is then an easy exercise that the I_k 's are the polynomial functions of a_i 's and b_j^2 's, i.e. $I_k(a_i, b_j) = I_k(a_i, -b_j)$ for $k = 1, \dots, l$. This implies that each connected component $Z_\epsilon(\gamma)$ labeled by the signs of b_i 's is just a copy of one single component, say $Z^+(\gamma)$ having all $b_i > 0$ (in Section 2, the topology of $Z^+(\gamma)$ and its closure $\overline{Z}^+(\gamma)$ will be discussed in detail). Then Tomei's manifold is considered as a smooth compactification of those components under a prescribed gluing through the boundaries, in fact, the manifold has a CW-decomposition with the cells marked by sequences of signs and zeros of b_i 's. The smoothness of the manifold was shown by giving local charts using the Toda flow (Lemma 2.1, 2.2 in [12]). This can be also shown by considering the manifold as a Morse complex associated with the Toda flow which gives

a *gradient-like* flow on the manifold. The Morse function $f : \overline{Z}(\gamma) \rightarrow \mathbb{R}$ is given by

$$f(X) = \sum_{i=1}^l (l-i+1)a_i, \quad (1.9)$$

where $\overline{Z}(\gamma)$ is the closure of the isospectral set (see also [2] for the Morse functions for the generalized Toda lattices on the semisimple Lie algebras). All the critical points of the function are then given by the diagonal matrices with the $(l+1)!$ permutation of $(\lambda_1, \dots, \lambda_{l+1})$, i.e. all $b_i = 0$. One can also show that near the critical point $(\lambda_{\sigma(1)}, \dots, \lambda_{\sigma(l+1)})$ with a permutation $\sigma \in S_{l+1}$, the symmetry group of order $l+1$, the Morse function takes the form,

$$f(X) = \sum_{i=1}^l (l-i+1)\lambda_{\sigma(i)} - \sum_{i=1}^l \frac{1}{\lambda_{\sigma(i)} - \lambda_{\sigma(i+1)}} b_i^2 + o(b_k^2).$$

This formula is useful for identifying all the handle bodies in the Morse decomposition of the manifold. However, our primary interest in this paper is not Morse theory; we will leave that for a future communication.

In this paper, we consider an extension of this Tomei manifold based on a twisted action of the Weyl group, the symmetry group for the example of this section. We start with the theorem due to Bloch et al in the case of a Lie algebra of type A_l [3] (which is summarized in its general Lie theoretic setting in subsection 2.1 below):

Remark 1.1. *The imbedding ι .*

The isospectral manifold $\overline{Z}^+(\gamma)$ in (1.8) is the closure of a generic noncompact torus orbit in \mathcal{O}_Λ of (1.4), with an action which does not agree with usual action of a split Cartan subgroup (the real diagonal matrices of determinant one) on $\overline{Z}^+(\gamma)$. This poses a difficulty in the application of a Convexity Theorem of Atiyah in [1] to this situation. However there is another imbedding ι described in [3] which corrects this difficulty.

The following is an A_l version of the main theorem in [3]:

Theorem 1.1. *There is an imbedding $\iota : \overline{Z}^+(\gamma) \hookrightarrow \mathcal{O}_\Lambda$ such that its image is the closure of an orbit under the usual action of real diagonal matrices of determinant one (a split Cartan subgroup). Using Atiyah's theorem [1], the image of the moment map $\Gamma := J \circ \iota(\overline{Z}^+(\gamma))$ where $J : X \in \mathcal{O}_\Lambda \rightarrow \text{diag}X$ is orthogonal projection, is the convex polytope with vertices at the critical points of the Morse function (1.9), that is, of the orbit of the Weyl group S_{l+1} of the Lie algebra $\mathfrak{sl}(l+1)$.*

The theorem can be applied to each isospectral leaf $\overline{Z}_\epsilon(\gamma)$ with different signs $\epsilon \in \mathcal{E}$ of (1.3). Then Tomei's manifold M_T is the union of those convex polytopes attached along the boundaries, and the Weyl group acts on each polytope independently. Thus the Tomei manifold can be described as the union of the polytopes Γ_ϵ associated with the isospectral leaves \overline{Z}_ϵ ,

$$M_T = \bigcup_{\epsilon \in \mathcal{E}} \Gamma_\epsilon. \quad (1.10)$$

The main idea of the present paper is to consider a twisted action of the Weyl group on the signs in \mathcal{E} , and based on this group action with specific sign change, we construct a smooth gluing between the Weyl chambers inside the polytopes with different signs.

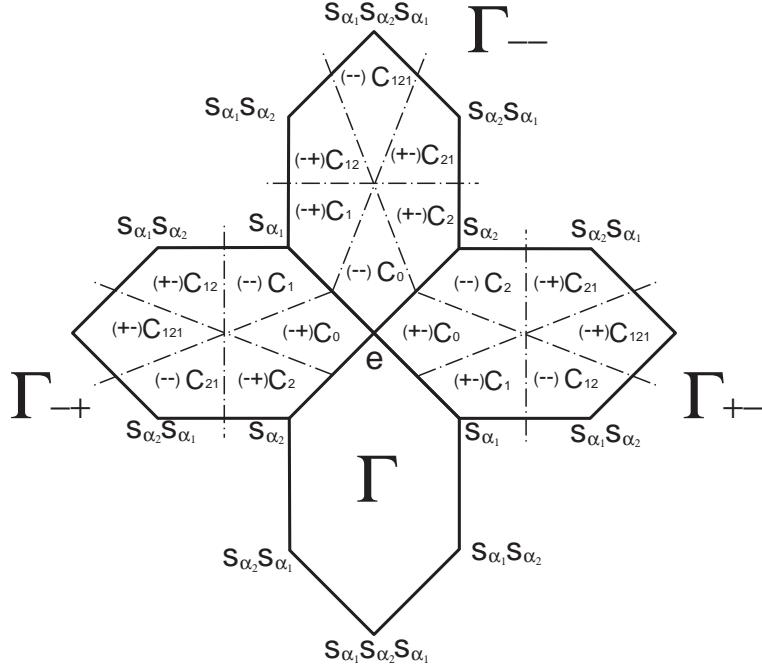


FIGURE 1.1. The polytopes Γ_ϵ with a standard S_3 -action. Chambers $C_{w^{-1}}$ are marked as C_0 for $w = e$, C_1 for $w = s_{\alpha_1}$ and so on.

This is consistent with the Toda flow, since the Morse function generating the flow depends only on $\{b_i^2 : i = 1, \dots, l\}$ and so does the Toda flow. Note that a point of the change of signs occurs at the same point on the same chamber walls of the polytopes with corresponding signs, so that the resulting flow stays smooth and provides a smooth gluing along the chamber walls.

Let us explain the result with an explicit example of $l = 2$. The polytope is then the hexagon with the six vertices corresponding to the permutation of $\lambda_1, \lambda_2, \lambda_3$, which are the critical points of the Morse function (1.9). We here assume $\lambda_1 > \lambda_2 > \lambda_3$. Each Weyl chamber contains one critical point which is marked by the corresponding element of the Weyl group. In particular, the critical point in the dominant chamber is associated with the fixed point $X_0 = \text{diag}(\lambda_1, \lambda_2, \lambda_3)$ of the Toda flow. The polytope Γ is now divided into the six Weyl chambers $C_w, w \in S_3$, and we let denote Γ_ϵ the polytope which has the sign ϵ in the dominant chamber and has a prescribed gluing along the inner walls of the chambers,

$$\Gamma_\epsilon = \bigcup_{w \in S_3} \{w\epsilon\} \times \overline{C}_{w^{-1}}. \quad (1.11)$$

where \overline{C}_w is the closure of C_w (see Figure 1.1). Here C_w describes the chamber containing the critical point wx_0 with $x_0 = J(X_0)$. The prescribed gluing is given by the S_3 -action on $\mathcal{E} = \{\pm 1\}^2$, and our smooth compact manifold has an expression,

$$M(\delta) = \bigcup_{\epsilon \in \{\pm 1\}^2} \Gamma_\epsilon, \quad (1.12)$$

where δ denotes the Dynkin diagram $\bullet - \bullet$ having a sign $+$ or $-$ on the edge, which specifies the S_3 -action on the sign. This marked Dynkin diagram is defined in Definition 3.3. If the action is trivial, $w\epsilon = \epsilon, \forall w \in S_3, \forall \epsilon \in \mathcal{E}$ (the corresponding marked Dynkin diagram is $\delta = \bullet^+ - \bullet$), then we have the Tomei manifold (1.10) which is topologically equivalent to the connected sum of two torus. If the action is a standard one with $s_{\alpha_i} \in S_3 : \epsilon_j \mapsto \epsilon_j \epsilon_i^{C_{j,i}}$ with $(C_{i,j})$ the Cartan matrix for A_2 (then $\delta = \bullet^- - \bullet$), we obtain the compact manifold corresponding to the indefinite Toda equation discussed in [10, 4] which is equivalent to the connected sum of two Klein bottles.

The paper is organized as follows:

In Section 2, we present the background information on the Toda lattice on the variety of ad-diagonalizable Jacobi elements with nonnegative signs. Then the convex polytope of the Weyl orbit associated with the Toda lattice is introduced based on the Convexity Theorem due to Bloch et al [3]. We also present the cell decomposition consisting of the Weyl chambers and their walls.

In Section 3, we define a twisted action of the Weyl group on the set of signs $\mathcal{E} = \{\pm 1\}^l$. We also introduce a marked Dynkin diagram where all the edges are assigned the signs which parametrizes a twisted sign action of the Weyl group (Definition 3.3). Then we obtain the number of compatible twisted action of the Weyl group (Proposition 3.1).

In Section 4, we construct a twisted Tomei manifold associated with a marked Dynkin diagram by defining gluing maps along both external and internal Weyl chamber walls. The manifold is then shown to have the structure of a smooth and compact manifold with a Weyl group action (Proposition 4.1). A cell decomposition of the manifold is also obtained in terms of signed colored Dynkin diagrams introduced in [4]. Then we conclude that the manifold is not orientable if the marked Dynkin diagram has at least one negative sign on the edge (Proposition 4.3), and the homology groups over $\mathbb{Z}/2\mathbb{Z}$ of all the twisted Tomei manifolds are the same as that of the original Tomei manifold (Theorem 4.1).

We then expect that the universal cover of the twisted Tomei manifold $M(\delta)$ is diffeomorphic to \mathbb{R}^l , hence $M(\delta)$ is also aspherical. Also we would like to mention that the homology group $H_*(M(\delta), \mathbb{Z})$ can be computed by the cell decomposition given in section 4.2, but an explicit computation remains open. Since the twisted Tomei manifolds have a common Morse function with different gluing (attaching) maps, the Morse theory might be useful for a further study of the manifolds.

2. TODA LATTICE WITH NON-NEGATIVE SIGNS

In this paper, we use the following standard Lie theoretic notation:

Notation 2.1. *Lie algebras:*

Let \mathfrak{g} denote a real split semisimple Lie algebra of rank l with Killing form $(,)$, universal enveloping algebra $U(\mathfrak{g})$ and we let $\mathfrak{g}' = Hom_{\mathbb{R}}(\mathfrak{g}, \mathbb{R})$ denote the dual of \mathfrak{g} . Fix a Cartan decomposition $\mathfrak{g} = \mathfrak{k} + \mathfrak{p}$ with \mathfrak{k} the Lie algebra of a maximal compact Lie group K . We also fix a split Cartan subalgebra $\mathfrak{h} \subset \mathfrak{p}$ with root system Δ , real root vectors e_{α_i} associated with simple roots $\{\alpha_i : i = 1, \dots, l\} = \Pi$. Denote $\{h_{\alpha_i}, e_{\pm \alpha_i}\}$

the Cartan-Chevalley basis of \mathfrak{g} which satisfies the relations,

$$[h_{\alpha_i}, h_{\alpha_j}] = 0, \quad [h_{\alpha_i}, e_{\pm\alpha_j}] = \pm C_{j,i} e_{\pm\alpha_j}, \quad [e_{\alpha_i}, e_{-\alpha_j}] = \delta_{i,j} h_{\alpha_j}. \quad (2.1)$$

where the $l \times l$ matrix $(C_{i,j})$ is the Cartan matrix corresponding to \mathfrak{g} , and $C_{i,j} = \alpha_i(h_{\alpha_j}) = \langle \alpha_i, h_{\alpha_j} \rangle$. The Weyl group W is thus generated by the simple reflections s_{α_i} , $i = 1, \dots, l$. For any $S \subset \Pi$, we define the subgroup generated by S ,

$$W_S = \langle s_{\alpha_i} : \alpha_i \in S \rangle \quad (2.2)$$

This is the Weyl group of a parabolic Lie subgroup and it is standard to refer to W_S as a *parabolic subgroup* of W .

Notation 2.2. *Lie groups:*

We let $G_{\mathbb{C}}$ denote the connected adjoint Lie group with Lie algebra $\mathfrak{g}_{\mathbb{C}}$ and G the connected Lie subgroup corresponding to \mathfrak{g} . We fix a maximal compact Lie group U of $G_{\mathbb{C}}$ and assume that $U \cap G = K$ with Lie algebra \mathfrak{k} .

Denote by \tilde{G} the Lie group $\{g \in G_{\mathbb{C}} : Ad(g)\mathfrak{g} \subset \mathfrak{g}\}$. A split Cartan of \tilde{G} with Lie algebra \mathfrak{h} will be denoted by $H_{\mathbb{R}}$; this Cartan subgroup has exactly 2^l connected components and the component of the identity is denoted by H . We let χ_{α_i} denote the roots characters, defined on $H_{\mathbb{R}}$.

Example 2.1.

If $G = Ad(SL(n, \mathbb{R}))$, \tilde{G} is isomorphic to $SL(n, \mathbb{R})$ for n odd and to $Ad(SL(n, \mathbb{R})^{\pm})$. This example is the underlying Lie group for the indefinite Toda lattices as shown in [4]. We have in this case $U = Ad(SU(n))$, $K = Ad(SO(n))$.

2.1. Variety of ad-diagonalizable Jacobi elements and its closure. As in the introduction, we let Z^+ denote the set of Jacobi elements with positive signs in the coefficients of $\mathfrak{g}_{\alpha} \in \mathfrak{g}$ with $\alpha \in \pm\Pi$, and \overline{Z}^+ denote its closure,

$$Z^+ = \left\{ X = x + \sum_{i=1}^l b_i (e_{\alpha_i} + e_{-\alpha_i}) \in \mathfrak{g} : x \in \mathfrak{h}, b_i > 0 \right\} \quad (2.3)$$

$$\overline{Z}^+ = \left\{ X = x + \sum_{i=1}^l b_i (e_{\alpha_i} + e_{-\alpha_i}) \in \mathfrak{g} : x \in \mathfrak{h}, b_i \geq 0 \right\} \quad (2.4)$$

We then define an isospectral leaf in \overline{Z}^+ as the fundamental object of our study:

Definition 2.1. *Fundamental invariants and isospectral leaves:*

Let $S(\mathfrak{g})$ be the symmetric algebra of \mathfrak{g} . We may regard $S(\mathfrak{g})$ as the algebra of polynomial functions on the dual \mathfrak{g}' . If we consider the algebra of G -invariants of $S(\mathfrak{g})$, then by Chevalley's theorem there are homogeneous polynomials I_1, \dots, I_l in $S(\mathfrak{g})^G$ which are algebraically independent and which generate $S(\mathfrak{g})^G$. According to Chevalley's theorem, we can then express $S(\mathfrak{g})^G$ as $\mathbb{R}[I_1, \dots, I_l]$. The functions I_1, \dots, I_l which are now polynomials on \mathfrak{g} can be further restricted to Z^+ . This gives rise to a map function $\mathcal{I} = (I_1, \dots, I_l)$ and its restriction $\mathcal{I} : Z^+ \rightarrow \mathbb{R}^l$. We consider the isospectral leaf $Z^+(\gamma) = \mathcal{I}^{-1}(\gamma)$ for any $\gamma \in \mathbb{R}^l$ in the image of \mathcal{L} . Denote by $\overline{Z}^+(\gamma)$ the closure of $Z^+(\gamma)$ inside \overline{Z}^+ .

2.2. Moment map and convexity. We recall the Convexity Theorem proven in [3] for the isospectral manifold $\overline{Z}^+(\gamma)$. Let ι be the imbedding defined in [3] (main theorem in section 3) of $\overline{Z}^+(\gamma)$ into an adjoint U orbit whose intersection with \mathfrak{g} we denote \mathcal{O}_Λ in \mathfrak{g}_C .

Consider the *moment map* associated to the U orbit and restricted to \mathfrak{g} : $J : \mathcal{O}_\Lambda \rightarrow \mathfrak{h}$. This is also the map obtained by orthogonal projection of \mathfrak{g} to \mathfrak{h} and then restriction to \mathcal{O}_Λ . Then the composition $J \circ \iota$ has as image the convex hull of a Weyl group orbit Wx_o with $x_o \in \mathfrak{h}$ as in section 4.1 in [3]. We denote the convex hull as

$$\Gamma = J \circ \iota(\overline{Z}^+(\gamma)) \quad (2.5)$$

The two objects $\overline{Z}^+(\gamma)$ and Γ are *manifolds with boundary*. The map $J \circ \iota$ is *homeomorphism* according to the Convexity Theorem in [3] and a diffeomorphism in the interior.

Such a convex hull is necessarily stable under the ordinary W action on \mathfrak{h} . Moreover there is a diffeomorphism between H and the interior of Γ of manifolds with a W action.

2.3. Internal and external walls of Γ . We here devide the polytope Γ into the Weyl chambers, and introduce the notations to describe them. We first denote C'_e as the dominant chamber in \mathfrak{h} intersected with Γ and \overline{C}'_e the corresponding closure, and also denote $C'_w = w(C'_e)$. We define $C_w = \{w\} \times C'_w$ and its closure $\overline{C}_w = \{w\} \times \overline{C}'_w$. The C'^{\dots} will refer to subsets of Γ , and we have the convention:

$$C_w^{\dots} = \{w\} \times C_w'^{\dots} \quad (2.6)$$

in all our notation concerning walls.

For each simple root α_i we may consider the corresponding α_i (internal) chamber wall intersected with \overline{C}'_w . Denote this set by $C_w'^{\alpha_i, IN}$. Each external wall of the convex hull of Wx_o is parametrized by a simple roots α_i . We denote an *external* wall of Γ by $C_w'^{\alpha_i, OUT}$ if it intersects all the *internal* chamber walls except for $C_w'^{\alpha_i, IN}$.

For any $A \subset \Pi$ we define the subsets of \overline{C}'_w of dimension $|\Pi \setminus A|$,

$$\begin{aligned} C_w'^{A, \Theta} &= \bigcap_{\alpha_i \in A} C_w'^{\alpha_i, \Theta}, & \text{if } A \neq \emptyset, \\ C_w'^{A, \Theta} &= C_w', & \text{if } A = \emptyset, \end{aligned} \quad (2.7)$$

where Θ is either *OUT* or *IN*. Thus we have the decomposition,

$$\overline{C}'_w = \bigcup_{\substack{A \subset \Pi \\ \Theta \in \{OUT, IN\}}} C_w'^{A, \Theta}. \quad (2.8)$$

2.4. Toda flow on Γ and its unstable manifolds. Denote by $\psi_t : \overline{Z}^+(\gamma) \rightarrow \overline{Z}^+(\gamma)$ the Toda flow on $Z^+(\gamma)$ and its boundary. For each t this gives a diffeomorphism of $\overline{Z}^+(\gamma)$ with itself of manifolds with boundary (see §2 of [11] for definitions).

The map $J \circ \iota$ between $\overline{Z}^+(\gamma)$ and Γ allows us to obtain a Toda flow on Γ . Namely we have the Toda flow $\phi_t : \Gamma \rightarrow \Gamma$ with

$$\phi_t = J \circ \iota \circ \psi_t \circ (J \circ \iota)^{-1}. \quad (2.9)$$

This flow preserves the boundary of Γ and, the image of the critical points of ψ_t are points in the W orbit of $x_o \in C_e'^{\Pi, OUT}$, the critical point in the dominant chamber. The *closures* of the unstable manifolds of the Toda flow on Γ are easily described as follows. First we define the unstable Weyl group $W^u(w)$ associated to the critical point $w^{-1}x_o$ with $w \in W$,

$$W^u(w) = W_{\Pi^u(w)} \text{ with } \Pi^u(w) := \{\alpha_i : \ell(s_{\alpha_i} w) > \ell(w)\}, \quad (2.10)$$

where $\ell(w)$ denotes the length of $w \in W$. We also define $\Pi^s(w) := \Pi \setminus \Pi^u(w)$.

The closure of the unstable manifold associated to the critical point $w^{-1}x_o$ is then the union

$$C'^u(w) = \bigcup_{\substack{\sigma \in W^u(w) \\ B \supset \Pi^s(w)}} C'^{B, OUT}_{(\sigma w)^{-1}} \quad (2.11)$$

2.5. Boundaries and cell decomposition . The chamber $\overline{C'_w}$ is a *box*. Fix two disjoint subsets $A, S \subset \Pi$, $A \cap S = \emptyset$. Then each intersection $C'^{A, OUT}_w \cap C'^{S, IN}_w$ is also a box of dimension $|\Pi \setminus (A \cup S)|$. These cells can be parametrized as the triples $(A; S; [w]_{\Pi \setminus S})$ with $[w]_{\Pi \setminus S} \in W/W_S$ the coset of w ,

$$(A; S; [w]_{\Pi \setminus S}) = C'^{A, OUT}_w \cap C'^{S, IN}_w. \quad (2.12)$$

With this notation, we also have the parametrizations

$$C'^{A, OUT}_w = (A; \emptyset; w), \quad C'^{S, IN}_w = (\emptyset; S; [w]_{\Pi \setminus S}).$$

We denote the faces of $(A; S; [w]_{\Pi \setminus S})$ by $\partial_{j,c}(A; S; [w]_{\Pi \setminus S})$ with $i = 1, \dots, l$ and $c = 1, 2$, which are defined as

$$\begin{aligned} \partial_{j,1}(A; S; [w]_{\Pi \setminus S}) &= (A \cup \{\alpha_j\}; S; [w]_{\Pi \setminus S}) \\ \partial_{j,2}(A; S; [w]_{\Pi \setminus S}) &= (A; S \cup \{\alpha_j\}; [w]_{\Pi \setminus (S \cup \{\alpha_j\})}) \end{aligned} \quad (2.13)$$

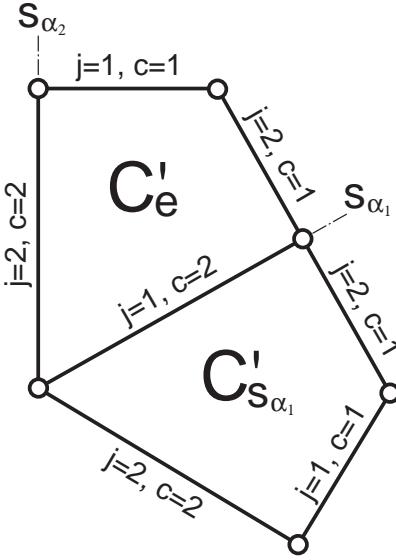
We then define \mathcal{M}_k the k -chain complex consisting of those cells,

$$\mathcal{M}_k = \mathbb{Z} \left[(A; S; [w]_{\Pi \setminus S}) : A, S \subset \Pi, A \cap S = \emptyset, k = |\Pi \setminus (A \cup S)|, w \in W \right] \quad (2.14)$$

To obtain cancellations along the walls of Γ we introduce signs $(-1)^{\ell(w)}$ so that Γ viewed inside \mathcal{M}_l corresponds to the alternating sum:

$$\Gamma = \sum_{w \in W} (-1)^{\ell(w)} \{e\} \times C_{w^{-1}} \quad (2.15)$$

The need for the signs $(-1)^{\ell(w)}$, given our notational conventions, is illustrated in Figure 2.1. Inner walls have the same value of c on opposite sides of a wall and then require a sign $(-1)^{\ell(w)}$. Thus cancellations along the inner chamber walls result from the fact that two adjacent chambers correspond to Weyl group elements with lengths differing by one. The boundary of Γ becomes then a cycle.

FIGURE 2.1. Boundaries $\partial_{j,c} C'_{w^{-1}}$ for \mathfrak{g} of rank 2.3. TWISTED ACTIONS OF W

3.1. Twisted W action on \mathcal{E} . The Weyl group associated to the Cartan subgroup $H_{\mathbb{R}}$ is the quotient $W = N(H_{\mathbb{R}})/H_{\mathbb{R}}$ where $N(\cdots)$ denotes the *normalizer*. Here we consider the W -action on the set of signs,

$$\mathcal{E} = \{(\epsilon_1, \dots, \epsilon_l) : \epsilon_i = \pm 1 \text{ for all } i = 1, \dots, l\} \quad (3.1)$$

with a group structure of multiplication $\bullet : \mathcal{E} \times \mathcal{E} \rightarrow \mathcal{E}$,

$$(\epsilon_1, \dots, \epsilon_l) \bullet (\epsilon'_1, \dots, \epsilon'_l) = (\epsilon_1 \epsilon'_1, \dots, \epsilon_l \epsilon'_l). \quad (3.2)$$

The group \mathcal{E} parametrizes the connected components of $H_{\mathbb{R}}$, and it is also in correspondence with the set of all elements $h \in H_{\mathbb{R}}$ such that the simple root characters $\chi_{\alpha_i}(h)$ have absolute value one, i.e.

$$H_{\mathbb{R}} = \bigcup_{\epsilon \in \mathcal{E}} h_{\epsilon} H, \quad \text{with} \quad \chi_{\alpha_i}(h_{\epsilon}) = \epsilon_i. \quad (3.3)$$

Let us now define:

Definition 3.1. *Twisted actions of the Weyl group on \mathcal{E} :*

We call an action of W on \mathcal{E} a *twisted sign action* if there is a matrix of integers $a_{i,j}$ with $i, j \in \{1, \dots, l\}$ and $a_{i,i} = 2$ (or just even) such that for each α_i the action $s_{\alpha_i} \in W : \mathcal{E} \rightarrow \mathcal{E}$ is given by

$$s_{\alpha_i} : \epsilon_j \mapsto \epsilon_j \epsilon_i^{a_{j,i}}. \quad (3.4)$$

Two canonical examples are the usual W action on $H_{\mathbb{R}}/H$ (and thus on \mathcal{E}) where $a_{i,j} = -C_{i,j}$ the Cartan matrix (recall $s_{\alpha_i} \chi_{\alpha_j} = \chi_{\alpha_j} \chi_{\alpha_i}^{-C_{j,i}}$), and the trivial W action where $a_{i,j}$ is even for all i, j .

By (3.4) the action of s_{α_i} on any $\epsilon = (\epsilon_1, \dots, \epsilon_l)$ such that $\epsilon_i = 1$ is trivial. Hence the only relevant cases happen when $\epsilon_i = -1$. For each pair of simple roots α_i, α_j $i < j$ which are connected in the Dynkin diagram, we define

$$s_{ij} = \epsilon_i^{a_{j,i}} = (-1)^{a_{j,i}} \quad (3.5)$$

Note that (3.4) ensures that any W action in Definition (3.1) necessarily acts on \mathcal{E} by group automorphisms. To see this we write the j th components of $s_{\alpha_i}(\epsilon \bullet \epsilon')$ and $s_{\alpha_i}\epsilon \bullet s_{\alpha_i}\epsilon'$; these are respectively $(\epsilon_i \epsilon'_i)^{a_{j,i}} \epsilon_j \epsilon'_j$ and $\epsilon_i^{a_{j,i}} \epsilon_j(\epsilon')^{a_{j,i}} \epsilon'_j$.

The twisted sign actions can be defined by first modifying the usual action of W on a split Cartan subgroup. The following definition describes the kind of modification that leads to Definition (3.1):

Definition 3.2. *Twisted action of the Weyl group on $H_{\mathbb{R}}$:*

Denote by $*$ the usual action of W on the Cartan subgroup $H_{\mathbb{R}}$. An action of W on $H_{\mathbb{R}}$ is said to be a *twisted action* if it satisfies

1. W acts on H with the usual action; moreover if $\chi_{\alpha_i}(h)$ is positive, then $s_{\alpha_i}h = s_{\alpha_i} * h$
2. each $w \in W$ acts as a Lie group automorphism of $H_{\mathbb{R}}$ and thus $w(h_1 h_2) = w(h_1)w(h_2)$ for any pair of elements h_1, h_2 in $H_{\mathbb{R}}$.

Note that any twisted action determines an action on the set of connected components $H_{\mathbb{R}}/H$ which is in bijective correspondence with the set of signs \mathcal{E} . The actions obtained in this way , starting from Definition (3.2), give rise to the twisted sign actions.

3.2. The rank 2 cases . We abuse notation slightly denoting by s_{α_i} what should be $A(s_{\alpha_i})$ for an appropriate group homomorphism $A : W \rightarrow Aut\mathcal{E}$. In these cases, an easy calculation shows (see also below) that the pair of signs (s_{12}, s_{21}) always determine constructions which satisfy relations of the following kinds

$$\begin{aligned} (s_{\alpha_i} s_{\alpha_j})^2 &= e & s_{12} &\neq s_{21} \\ (s_{\alpha_i} s_{\alpha_j})^3 &= e & s_{12} &= s_{21} = -1 \end{aligned} \quad (3.6)$$

By squaring the first relation one obtains $(s_{\alpha_i} s_{\alpha_j})^4 = e$ and by squaring the second one obtains $(s_{\alpha_i} s_{\alpha_j})^6 = e$. Thus the first case is compatible with the braid relation of W in B_2 and G_2 and the second is compatible with the cases of A_2 and G_2 . We thus list the twisted sign actions in all these cases.

Example 3.1.

We just illustrate what is involved in checking (3.6) by working out the case, $s_{12} = -1$ and $s_{21} = 1$. For example, if we apply $(s_{\alpha_2} s_{\alpha_1})^2$ to $(-1, -1)$ we get again $(-1, -1)$ as demonstrated below:

$$(-1, -1) \xrightarrow{s_{\alpha_1}} (-1, 1) \xrightarrow{s_{\alpha_2}} (-1, 1) \xrightarrow{s_{\alpha_1}} (-1, -1) \xrightarrow{s_{\alpha_2}} (-1, -1). \quad (3.7)$$

Similarly we obtain that $(s_{\alpha_2}s_{\alpha_1})^2$ gives the identity by considering all the other cases. Hence the relation $(s_{\alpha_2}s_{\alpha_1})^2 = e$ is obtained for $s_{12} \neq s_{21}$ as in (3.6).

Example 3.2. *The twisted sign actions in A_2 :*

The only non-trivial twisted sign action corresponds to $s_{12} = -1$ and $s_{21} = -1$, the standard sign action, and it is given explicitly by

$$\begin{aligned} s_{\alpha_1}(\epsilon_1, \epsilon_2) &= (\epsilon_1, \epsilon_1\epsilon_2) \\ s_{\alpha_2}(\epsilon_1, \epsilon_2) &= (\epsilon_2\epsilon_1, \epsilon_2) \end{aligned} \quad (3.8)$$

Example 3.3. *The twisted sign actions of B_2 and C_2 :*

The only non-trivial possibilities here are the cases $s_{12} \neq s_{21}$. These become explicitly:

$$\begin{aligned} s_{\alpha_1}(\epsilon_1, \epsilon_2) &= (\epsilon_1, \epsilon_1\epsilon_2), \\ s_{\alpha_2}(\epsilon_1, \epsilon_2) &= (\epsilon_1, \epsilon_2), \end{aligned} \quad (3.9)$$

which is the standard action for B_2 and a twisted one for C_2 . We also have

$$\begin{aligned} s_{\alpha_1}(\epsilon_1, \epsilon_2) &= (\epsilon_1, \epsilon_2), \\ s_{\alpha_2}(\epsilon_1, \epsilon_2) &= (\epsilon_2\epsilon_1, \epsilon_2). \end{aligned} \quad (3.10)$$

for the standard case of C_2 and a twisted one of B_2 .

Example 3.4. *The twisted sign actions in G_2 :*

Assume that $C_{21} = 3$. In this case there are four possible specifications of the signs s_{12} and s_{21} and they all give twisted sign actions. The standard sign action corresponds to $s_{12} = -1$ and $s_{21} = -1$.

Definition 3.3. *Marked Dynkin diagrams*

A *marked* Dynkin diagram is a Dynkin diagram where all the single edges are assigned the sign + or -; any double edge is assigned a pair of signs +, + or \pm , \mp , and a triple edge (G_2) is assigned any pair of any signs \pm, \pm or \pm, \mp . Those signs associated to the edge joining α_i and α_j are given by s_{ij} or s_{ji} , and $s_{ij} = s_{ji}$ in the case of single edges in the Dynkin diagram.

We call a marked Dynkin diagram *positively marked* if all the signs s_{ij} over any of its edges are positive (the case when \mathfrak{g} is of type $A_1 \times \cdots \times A_1$ is always considered positive). A positively marked Dynkin diagram corresponds to a trivial action of W on \mathcal{E} . We call the marked Dynkin diagram *standard* in case that the matrix a_{ij} can be chosen to be the Cartan matrix. Given a marked Dynkin diagram and subset $B \subset \Pi$, there is a subdiagram δ_B corresponding to an action of W_B on a set of signs.

Proposition 3.1. *Assume that \mathfrak{g} is a simple Lie algebra. Let α denote the number of pairs of simple roots joined by a single edge in the Dynkin diagram and β the number of double edges. Then if \mathfrak{g} is not of type G_2 there are exactly $2^\alpha 3^\beta$ twisted signed*

actions of W parametrized by marked Dynkin diagrams. In the case of G_2 there are four such twisted signed actions. For any semisimple Lie algebra the twisted signed actions are parametrized by the set of marked Dynkin diagrams.

Proof. Recall that W is a Coxeter group, (Proposition 3.13 [9]) and it thus has defining relations $s_{\alpha_i}^2 = e$ and $(s_{\alpha_i} s_{\alpha_j})^{m_{ij}} = e$ where m_{ij} is 2, 3, 4, 6 depending on the number of lines joining α_i and α_j in the Dynkin diagram. The case $m_{ij} = 2$ occurring when α_i and α_j are not connected in the Dynkin diagram. From the definition of a twisted signed action of W on \mathcal{E} , such an action is completely determined if one specifies all the signs $s_{ji} := (s_{\alpha_i} \epsilon)_j$ where α_j is joined in the Dynkin diagram to α_i . It is then enough to count all the possible choices s_{ij} and s_{ji} giving rise to $(s_{\alpha_i} s_{\alpha_j})^{m_{ij}} = e$; the other relation being automatically satisfied. This then reduces the proof to the classification of all twisted signed W actions in the cases A_2 , B_2 , G_2 , namely the examples (3.2), (3.3) and (3.4) in subsection (3.2). To a marked Dynkin diagram we thus associate a twisted sign action of W where the signs $s_{i,j}$ defining the action are given as in definition (3.3). \square

4. THE TWISTED TOMEI MANIFOLDS

For each marked Dynkin diagram δ corresponding to a twisted sign action we associate a compact smooth manifold with an action of W . We call the manifold the twisted Tomei manifold, and here give a construction of the manifold by gluing the chamber walls of the polytopes associated with different $\epsilon \in \mathcal{E}$:

Let δ denote a marked Dynkin diagram giving rise to a fixed twisted sign action of W . Recall *external* and *internal* chamber walls which constitute the boundary of Γ and were described above.

We then define gluing maps between the chamber walls denoted by $\{\epsilon\} \times C_w^{\dots} = \{\epsilon\} \times \{w\} \times C_w'^{\dots}$ as follows: For the internal walls, we define

$$\begin{aligned} g_{w,i,IN} : \quad & \{\epsilon\} \times C_w^{\alpha_i, IN} \rightarrow \{s_{\alpha_i} \epsilon\} \times C_{ws_{\alpha_i}}^{\alpha_i, IN} \\ & (\epsilon, w, x) \longmapsto (s_{\alpha_i} \epsilon, ws_{\alpha_i}, x) \end{aligned} \tag{4.1}$$

where note $ws_{\alpha_i}w^{-1}x = x$. For the external walls, we define

$$\begin{aligned} g_{w,i,OUT} : \quad & \{\epsilon\} \times C_w^{\alpha_i, OUT} \rightarrow \{\epsilon^{(i)}\} \times C_w^{\alpha_i, OUT} \\ & (\epsilon, w, x) \longmapsto (\epsilon^{(i)}, w, x) \end{aligned} \tag{4.2}$$

where $\epsilon^{(i)} = (\epsilon_1, \dots, -\epsilon_i, \dots, \epsilon_l)$. We denote $\tilde{M}(\delta)$ the disjoint union of all the chambers with different signs,

$$\tilde{M}(\delta) = \bigcup_{\substack{w \in W \\ \epsilon \in \mathcal{E}}} \{w\epsilon\} \times \overline{C}_{w^{-1}}. \tag{4.3}$$

We also denote $M(\delta)$ the topological space obtained from the disjoint union in (4.3) by gluing along the internal and external walls using the maps $g_{w,i,IN}$ and $g_{w,i,OUT}$. There is then a map

$$z : \tilde{M}(\delta) \rightarrow M(\delta). \tag{4.4}$$

We define an action of the group W on $\tilde{M}(\delta)$ by

$$\sigma \in W : (\epsilon, w, x) \mapsto (\epsilon, \sigma w, \sigma x). \tag{4.5}$$

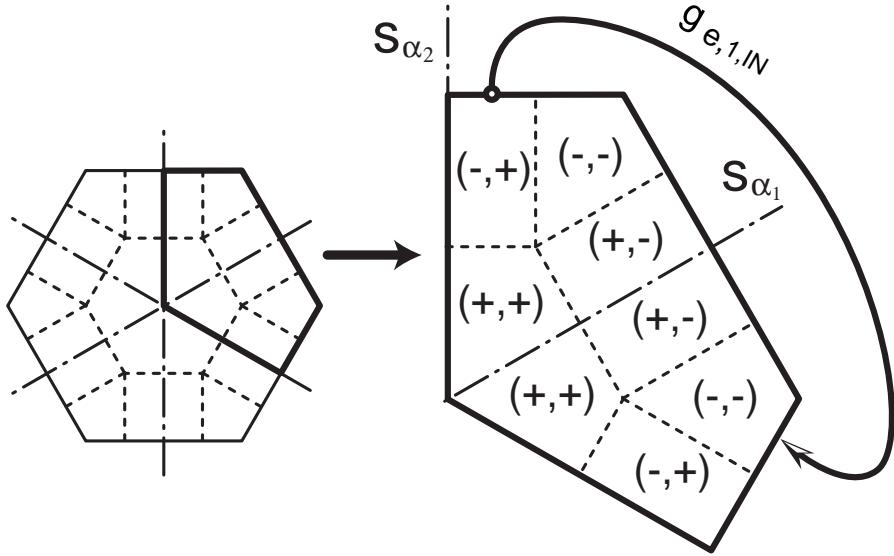


FIGURE 4.1. Standard case A_2 ; gluing by $g_{e,1,IN}$ along the internal walls of $\{(-,+)\} \times C_e^{\alpha_1,IN}$ and $\{(-,-)\} \times C_{s_{\alpha_1}}^{\alpha_1,IN}$ reverses orientation (internal hexagon is Γ). External walls are glued along the dashed lines.

Lemma 4.1. *The action of W defined in (4.5) gives rise to a well defined action in $M(\delta)$.*

Proof. We must show that the action of W sends pairs of elements that are identified with each other to other pairs of elements that are identified. Consider first the case of the gluing maps for internal walls $g_{\dots,i,IN}$: Let the vertical arrows in (4.6) below correspond to multiplication by $\sigma \in W$; and assume the horizontal arrows are given by a gluing map of the form $g_{w,i,IN}$. We have:

$$\begin{array}{ccc} (\epsilon, w, x) & \xrightarrow{g_{w,i,IN}} & (s_{\alpha_i}\epsilon, ws_{\alpha_i}, x) \\ \sigma \downarrow & & \sigma \downarrow \\ (\epsilon, \sigma w, \sigma x) & \xrightarrow{g_{\sigma w,i,IN}} & (s_{\alpha_i}\epsilon, \sigma ws_{\alpha_i}, \sigma x) \end{array} \quad (4.6)$$

We thus obtain that the image of the first pair of points under the group action corresponds to another pair of points which are identified. The gluings along the external walls do not pose any difficulties either. \square

Remark 4.1.

Consider the union of the chambers with the signs determined by a twisted action of W corresponding to δ ,

$$\tilde{\Gamma}_\epsilon(\delta) = \bigcup_{w \in W} \{w\epsilon\} \times \overline{C}_{w^{-1}} \quad (4.7)$$

We let $\Gamma_\epsilon(\delta)$ denote the image of $\tilde{\Gamma}_\epsilon$ in $M(\delta)$. Then after the identifications in $M(\delta)$, this space becomes a copy of Γ (see Figure 1.1). We denote

$$F_\epsilon^\delta : \Gamma \longrightarrow \Gamma_\epsilon(\delta) \quad (4.8)$$

We note that each Γ_ϵ is usually *not* preserved by the W action. The union of the interiors of all the Γ_ϵ over $\epsilon \in \mathcal{E}$ can be identified with a copy of $H_{\mathbb{R}}$ and the W action would then correspond to the notion of a twisted W action on a Cartan subgroup. We can now express $M(\delta)$ as a union:

$$M(\delta) = \bigcup_{\epsilon \in \mathcal{E}} \Gamma_\epsilon(\delta). \quad (4.9)$$

Similarly we consider

$$\tilde{K}_e = \bigcup_{\epsilon \in \mathcal{E}} \{\epsilon\} \times \overline{C}_e \quad (4.10)$$

Denote by $K_e = z(\tilde{K}_e)$ its image in $M(\delta)$. This set is compact and constitutes a fundamental domain of the W action. Moreover K_e is a *box*. For example Figure 4.2 shows the union of K_e and $s_{\alpha_1}K_e$ in the A_2 case.

Proposition 4.1. *The space $M(\delta)$ has the structure of a smooth compact manifold with a W action.*

Proof. The space $M(\delta)$ has an action of W as defined in (4.5) and verified in (4.6) in Lemma 4.1. The compactness follows from the fact that W is finite and that the box K_e is compact because $W(K_e) = M(\delta)$. The smoothness is obtained using the coordinate charts given by the boxes $\{w(K_e) : w \in W\}$. \square

4.1. Toda flow on $M(\delta)$. Using the map F_ϵ^δ in (4.8), we define the Toda flow

$$\begin{aligned} \phi_t^\delta : & M(\delta) \longrightarrow M(\delta) \\ & (\epsilon, w, x) \mapsto F_\epsilon^\delta \circ \phi_t \circ (F_\epsilon^\delta)^{-1}(\epsilon, w, x) \end{aligned} \quad (4.11)$$

where ϕ_t is the Toda flow on Γ defined in (2.9).

Since the unstable manifolds for the Toda flow on Γ have been described in (2.11) we are now able to describe the *closures* $\overline{C}^u(w)$ of the unstable manifolds $C^u(w)$ of the new Toda flow in the twisted Tomei manifold.

Recall the map $z : \tilde{M}(\delta) \rightarrow M(\delta)$ in (4.4). Then we have

$$\overline{C}^u(w) = \bigcup_{\substack{\sigma \in W^u(w) \\ B \supset \Pi^s(w)}} z(\mathcal{E} \times C_{(\sigma w)^{-1}}^{B, OUT}) \quad (4.12)$$

Since the closures of unstable manifolds are constructed in the same way as the twisted Tomei manifolds with respect to a convex polytope associated to a parabolic subgroup of W , we have:

Proposition 4.2. *For any $w \in W$, the closure of the unstable manifold $\overline{C}^u(w)$ is smooth. Moreover $\overline{C}^u(w)$ is a twisted Tomei manifold for the Levi factor of a parabolic subgroup determined by $\Pi^u(w)$ with marked Dynkin diagram $\delta_{\Pi^u(w)}$ (see Definition 3.3).*

4.2. Cell decomposition of $M(\delta)$. We now describe a cell decomposition that is useful in our explicit description of all the unstable manifolds of the Toda lattice. This cell decomposition is not efficient in terms of computing homology because it contains too many cells; however a more efficient cell decomposition is described in [4] in the standard case. Unfortunately the Toda lattice is not a Morse-Smale vector field and consequently the boundary of an unstable manifold usually fails to be a combination of unstable manifolds. This problem is evident in Lemma 4.2 or in low dimensional examples (see also [5]).

Using the cell decomposition in subsection 2.5 we obtain a cell decomposition for $M(\delta)$ by simply adding a factor $\{\epsilon\} \times (\cdots)$ and applying z . Note here that because of the gluings between external walls in (4.2), the cells $z(\{\epsilon\} \times C'_w^{A,OUT} \cap C'_w^{S,IN})$ are not parametrized simply by the triples involving $\epsilon \in \mathcal{E}$ and $A, S \subset \Pi$. The value of ϵ_i for $\alpha_i \in A$ will be set to zero to avoid duplication of parameters. For any $A \subset \Pi$, we introduce

$$\mathcal{E}^A = \left\{ (\epsilon_1, \dots, \epsilon_l) : \epsilon_i = \pm 1 \text{ if } \alpha_i \notin A, \epsilon_i = 0 \text{ if } \alpha_i \in A \right\} \quad (4.13)$$

Note that $W_{\Pi \setminus A}$ acts on \mathcal{E}^A , the new zeros are irrelevant to the action.

Definition 4.1. *Signed colored Dynkin diagrams*

A *signed colored Dynkin diagram* is a triple $(\epsilon; A; S)$, where $\epsilon = (\epsilon_1, \dots, \epsilon_l)$ with $\epsilon_i = 0$ if $\alpha_i \in A$ (otherwise $\epsilon_i = \pm 1$) and $A, S \subset \Pi$ with $A \cap S = \emptyset$. This corresponds to the notion of signed colored Dynkin diagram in Definition (5.1.2) in [4]. There the simple roots in S are colored *blue* if $\epsilon_i = 1$, *red* if $\epsilon_i = -1$; and are given a sign $= \text{sign}\epsilon_i = \pm$ if the simple root is in $\Pi \setminus (A \cup S)$ and a zero if the simple root belongs to A .

Then the cell $\{\epsilon\} \times C'_w^{A,OUT} \cap C'_w^{S,IN}$ is parametrized by a signed colored Dynkin diagram,

$$\{\epsilon\} \times C'_w^{A,OUT} \cap C'_w^{S,IN} = (\epsilon; A; S; [w]_{\Pi \setminus S}) \quad (4.14)$$

The faces of this cell are then expressed as

$$\begin{aligned} \partial_{j,c}(\epsilon; A; S; [w]_{\Pi \setminus S}) &= (\epsilon; A \cup \{\alpha_j\}; S; [w]_{\Pi \setminus S}), & \text{if } (-1)^{c+1} = \epsilon_j \\ \partial_{j,c}(\epsilon; A; S; [w]_{\Pi \setminus S}) &= (\epsilon; A; S \cup \{\alpha_j\}; [w]_{\Pi \setminus (S \cup \{\alpha_j\})}), & \text{if } (-1)^c = \epsilon_j \end{aligned} \quad (4.15)$$

This is just (2.13) but all the 2^l signs are now used to form a bigger box as in Figure (4.2) and cancellations are required along the *external* walls (which have become internal in the box).

We now define the chain complex \mathcal{M}_* ,

$$0 \longrightarrow \mathcal{M}_l \xrightarrow{\partial_l} \mathcal{M}_{l-1} \xrightarrow{\partial_{l-1}} \dots \xrightarrow{\partial_2} \mathcal{M}_1 \xrightarrow{\partial_1} \mathcal{M}_0 \longrightarrow 0, \quad (4.16)$$

where the k -chain \mathcal{M}_k and the boundary map ∂_k are defined as

$$\mathcal{M}_k = \mathbb{Z} \left[(\epsilon; A; S; [w]_{\Pi \setminus S}) : A, S \subset \Pi, A \cap S = \emptyset, k = |\Pi \setminus (A \cup S)|, w \in W, \epsilon \in \mathcal{E} \right], \quad (4.17)$$

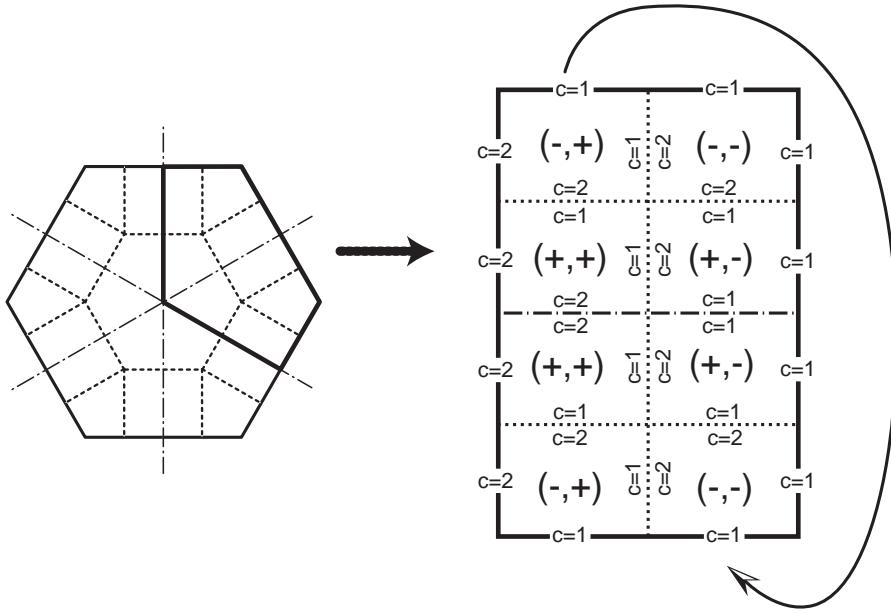


FIGURE 4.2. Boundaries $\partial_{j,c}$ for A_2 . Cancellations along the external walls are shown by the different choice of c .

$$\partial_k = \sum_{\substack{j=1, \dots, k \\ c=1,2}} (-1)^{j+c+1} \partial_{j,c}. \quad (4.18)$$

4.3. The boundaries of the unstable manifolds in $M(\delta)$. With the gluing along the walls, one needs to get the cancellations of the orientations of the glued chambers. This then leads to a change of orientation at the boundary. In order to obtain cancellations along the internal walls of Γ_ϵ we had introduced signs $(-1)^{\ell(w)}$ in (2.15). Recall (also see Figure 4.2) that external wall cancellations occur because c differs on two sides of the wall, and internal wall cancellations are produced by the different signs $(-1)^{\ell(w)}$. The exceptions to this are all the cases of non-trivial gluings that change the orientation; these orientation changes can only happen along the internal α_i walls satisfying $\epsilon_i = -1$ (*negative walls*). In these cases additional signs must be introduced to compensate orientation changes. For fixed w and ϵ we denote $(w\epsilon)_j$ the j -th component of $w\epsilon$. The cell Γ_ϵ can then be represented in \mathcal{M}_* by

$$\Gamma_\epsilon = \sum_{w \in W} (-1)^{\ell(w)} \left(\prod_{k=1, \dots, l} \epsilon_k (w\epsilon)_k \right) \{w\epsilon\} \times C_{w^{-1}} \quad (4.19)$$

The boundary of each Γ_ϵ becomes then a cycle and only contains external walls.

Example 4.1. *The case of A_n .*

We illustrate the derivation of the expression in (4.19) in the case of A_n . Canonical examples are the original Tomei manifold and the standard one (δ is positively marked or δ is marked with signs determined by the Cartan matrix as in Definition 3.3). The change of orientation of the boundary of K_e under the gluing $g_{w,i,IN}$ in (4.1), with $i = 1$ is determined by the number of ϵ_j that change sign under the action of s_{α_1} , that is by the sign of $\prod_{k=1, \dots, l} \epsilon_k (s_{\alpha_1} \epsilon)_k$. This number is 1 in the positively marked case

and -1 in the standard case. Therefore, to have cancellations at the internal wall boundaries we have to insert a sign $\prod_{k=1,\dots,l} \epsilon_k(s_{\alpha_1}\epsilon)_k$. If we now consider the α_2 wall of the new chamber $\{s_{\alpha_1}\epsilon\} \times C_{s_{\alpha_1}}$, the new sign $s_{\alpha_1}\epsilon$ gets changed under the gluing map to $s_{\alpha_2}s_{\alpha_1}\epsilon$. Thus the change of sign is given by the product $\prod_{k=1,\dots,l} (s_{\alpha_2}s_{\alpha_1}\epsilon)_k(s_{\alpha_1}\epsilon)_k$. However there is already a sign attached to this chamber, namely $\prod_{k=1,\dots,l} \epsilon_k(s_{\alpha_1}\epsilon)_k$ and the product of these two gives the new sign which becomes $\prod_{k=1,\dots,l} \epsilon_k(w\epsilon)_k$ with $w = s_{\alpha_2}s_{\alpha_1}$. This leads to the expression in (4.19).

The unstable manifold associated with $w \in W$ is now represented in \mathcal{M}_* by

$$C^u(w) = \sum_{\substack{\sigma \in W^u(w) \\ \epsilon \in \mathcal{E}^{\Pi^s(w)}}} (-1)^{\ell(\sigma)+\ell(w)} \left(\prod_{\alpha_k \in \Pi^u(w)} \epsilon_k(\sigma\epsilon)_k \right) \{\epsilon\} \times (\epsilon; \Pi^s(w); \emptyset; (\sigma w)^{-1}). \quad (4.20)$$

Here recall that $(\epsilon; \Pi^s(w); \emptyset; (\sigma w)^{-1}) = C_{(\sigma w)^{-1}}^{\Pi^s(w), OUT}$. The dimension of $C^u(w)$ is then given by $|\Pi^u(w)|$, and we call it the *index* of $w \in W$. Then we have:

Lemma 4.2. *Let $w \in W$ of index k . Then there is $X \in \mathcal{M}_{k-1}$ such that $\partial C^u(w) = 2X$. Explicitly we have*

$$\partial C^u(w) = 2(-1)^{\ell(w)+1} \sum_{\substack{\sigma \in W^u(w), \alpha_r \in \Pi^u(w) \\ \epsilon \in \mathcal{E}^{\Pi^s(w) \cup \{\alpha_r\}}}} \mu(\epsilon, r, \sigma)(\epsilon; \Pi^s(w) \cup \{\alpha_r\}; \emptyset; (\sigma w)^{-1}) \quad (4.21)$$

where the coefficient $\mu(\epsilon, r, \sigma)$ is given as

$$\begin{cases} (-1)^{\ell(\sigma)+r} \prod_{\alpha_j \in \Pi^u(w)} \epsilon(-r)_j(\sigma\epsilon(-r))_j, & \text{if } \prod_{\alpha_j \in \Pi^u(w)} (\sigma\epsilon(-r))_j(\sigma\epsilon(+r))_j = 1 \\ 0, & \text{if } \prod_{\alpha_j \in \Pi^u(w)} (\sigma\epsilon(-r))_j(\sigma\epsilon(+r))_j = -1 \end{cases} \quad (4.22)$$

where $\epsilon(\pm r) = (\epsilon_1, \dots, \pm 1, \dots, \epsilon_l)$ for $\epsilon \in \mathcal{E}^{\Pi^s(w) \cup \{\alpha_r\}}$.

Proof. We apply the definition of the boundary ∂ in (4.15) and (4.18) to the expression in (4.20). Then noticing $\epsilon_r = (-1)^{c+1}$ we obtain

$$\partial C^u(w) = (-1)^{\ell(w)} \sum_{\substack{\sigma \in W^u(w), \alpha_r \in \Pi^u(w) \\ \epsilon \in \mathcal{E}^{\Pi^s(w)}}} \nu(\epsilon, r, \sigma)(\epsilon[r]; \Pi^s(w) \cup \{\alpha_r\}; \emptyset; (\sigma w)^{-1}) \quad (4.23)$$

where $\epsilon[j] = (\epsilon_1, \dots, 0, \dots, \epsilon_l)$ for $\epsilon \in \mathcal{E}^{\Pi^s(w)}$, and $\nu(\epsilon, r, \sigma)$ is given by

$$\nu(\epsilon, r, \sigma) = (-1)^{\ell(\sigma)+r} \epsilon_r \prod_{\alpha_j \in \Pi^u(w)} \epsilon_j(\sigma\epsilon)_j \quad (4.24)$$

We will now simply collect terms with the same α_r but different sign ϵ_r . We then fix $\epsilon \in \mathcal{E}^{\Pi^s(w) \cup \{\alpha_r\}}$ so that $\epsilon(\pm r) \in \mathcal{E}^{\Pi^u(w)}$ with different signs in the r -th component. The coefficient of $(\epsilon; \Pi^s(w) \cup \{\alpha_r\}; \emptyset; (\sigma w)^{-1})$ becomes (with $\epsilon(-r)_r = -1$ by convention)

$$(-1)^{\ell(w)+r} (\epsilon(-r)_r) \left(\prod_{j \neq r} \epsilon(-r)_j \right) \left(\epsilon(-r)_r \prod_k (\sigma\epsilon(-r))_k + \epsilon(-r)_r \epsilon(r)_r^2 \prod_k (\sigma\epsilon(r))_k \right) \quad (4.25)$$

From (4.25) and since $\epsilon(-r)_r = -1$ and $\epsilon(r)_r = 1$, the only cases when a coefficient is zero are those for which:

$$\prod_k (\sigma\epsilon(-r))_k = - \prod_k (\sigma\epsilon(r))_k \quad (4.26)$$

We thus obtain (4.22) for the coefficients $\mu(\epsilon, r, \sigma)$. From here it follows that $\partial C^u(w) = 2X$. \square

We now have:

Proposition 4.3. *If δ is not a positively marked Dynkin diagram, then $M(\delta)$ is not orientable.*

Proof. assume that the marked Dynkin diagram δ has some negative sign $s_{i,j}$. By Lemma 4.2 it is enough to compute any of the coefficients in (4.22) and show that it is non-zero for the case of (4.19), the unstable manifold for $w = e$, the top cell. By picking a negatively marked edge as close as possible to one of the ends of the Dynkin diagram we can reduce the calculation to the rank two cases. This is an easy calculation which we illustrate in Example (4.2). \square

Example 4.2. *Non-orientability in the standard A_2 case.*

We compute one of the coefficients in (4.22). Consider $w = e$, $\Pi^s(w) = \emptyset$, $r = 1$, $\epsilon = (0, 1) \in \mathcal{E}^{\{\alpha_1\}}$, $\epsilon(-1) = (-1, 1)$ and $\epsilon(1) = (1, 1)$. Now for $\sigma = s_{\alpha_1}$, we obtain $\sigma(\epsilon(-1)) = (-1, -1)$ and $\sigma(\epsilon(1)) = (1, 1)$. Thus the product of all these signs is one and we have a non-zero boundary of the top cell (4.19).

Corollary 4.1. *The closure of an unstable manifold $\overline{C}^u(w)$ gives rise to a cycle in homology if and only if its marked Dynkin diagram $\delta_{\Pi^u(w)}$ is positively marked.*

Proof. We use Proposition (4.2) and Proposition (4.3) to conclude that $\overline{C}^u(w)$ is orientable- thus a cycle- exactly when $\delta_{\Pi^u(w)}$ is positively marked. \square

We now obtain in the standard case :

Corollary 4.2. *If $M(\delta)$ corresponds to the standard marked Dynkin diagram, then $\overline{C}^u(w)$ gives rise to a cycle in homology if and only if the unstable Weyl group $W^u(w)$ is abelian.*

Proof. In this case one observes that all the subdiagrams of standard marked Dynkin diagram remain standard. Hence these are not positively marked except in the case when there are no edges in the subdiagram and the corresponding Weyl group $W^u(w)$ is abelian. \square

Let $e(k)$ be the number of all elements in W with index k . For example, $e(k)$ is the Eulerian number $E(l+1, k)$ for \mathfrak{g} of type A_l (i.e. $W = S_{l+1}$, the symmetry group of order $l+1$). Then we have the following theorem which is a generalization to the manifolds $M(\delta)$ considered in [7].

Theorem 4.1. *Let δ be a marked Dynkin diagram. Then for any $k = 0, 1, \dots, l$ the homology group $H_k(M(\delta), \mathbb{Z}/2\mathbb{Z})$ has rank $e(k)$.*

Proof. This follows from Morse theory and from Lemma (4.2) which implies that all the unstable manifolds are cycles over $\mathbb{Z}/2\mathbb{Z}$. \square

Similarly, in the case of a Tomei manifold all the closures of unstable manifolds are orientable since the marked Dynkin diagrams $\delta_{\Pi^u(w)}$ of Corollary 4.1 are positively marked.

We then recover a theorem of Davis [6] (general setting of Coxeter groups) and Fried [8] (for type A_l):

Theorem 4.2. *In the case when $M(\delta)$ is a Tomei manifold, for any $k = 0, 1, \dots, l$ the homology group $H_k(M(\delta), \mathbb{Z})$ is free of rank $e(k)$.*

REFERENCES

1. M. F. Atiyah, Convexity and commuting Hamiltonians, *Bull. London Math. Soc.* **14** (1982) 1-15.
2. A. M. Bloch, R. W. Brockett and T. Ratiu, Complete integrable gradient flows, *Comm. Math. Phys.* **147** (1992) 57-74.
3. A. M. Bloch, H. Flaschka, T. Ratiu, A convexity theorem for isospectral manifolds of Jacobi matrices in a compact Lie algebra, *Duke Math Journal* **61** (1990) 41-65.
4. L. Casian and Y. Kodama, Toda lattice and toric varieties for real split semisimple Lie algebras. Preprint OSU-MRI 99-17 (1999) (math-sg/9912021), *Pacific J. of Math.* to be published.
5. L. Casian and Y. Kodama, Topology of the iso-spectral real manifolds associated with the generalized Toda lattices on semisimple Lie algebras, *J. Phys. A: Math. Gen.* (2001) in press.
6. M. W. Davis, Some aspherical manifolds, *Duke Math. J.* **55** (1987) 105-139.
7. M. W. Davis and T. Januszkiewicz, Convex polytopes, coxeter orbifolds and torus actions, *Duke Math. J.* **62** (1991) 417-451.
8. D. Fried, The cohomology of an isospectral flow, *Proc. Amer. Math. Soc.*, **98** (1986) 363-368.
9. V. Kac, Infinite dimensional Lie algebras, (Cambridge University Press, 1990).
10. Y. Kodama and J. Ye. Toda Lattices with indefinite metric II: Topology of the iso-spectral manifolds. *Physica D*, **121** (1998), 89-108.
11. J. Milnor, Topology from the differentiable viewpoint *The University Press of Virgionia Charlottesville* (1978).
12. C. Tomei. The topology of the isospectral manifolds of tridiagonal matrices. *Duke Mathematical Journal*, **51** (1984), 981-996.